

Asymptotic Stability in Functional Differential Equations

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함수 미분 방정식에서의 점근 안정성

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1. Introduction

This paper is concerned with the asymptotic stability of certain functional differential equations. The equation is investigated by means of Lyapunov's direct method.

In this discussion, $(C, \| \cdot \|)$ is the Banach space of continuous functions $\phi : [-h, 0] \rightarrow \mathbb{R}^n$, $\| \phi \| = \sup_{-h \leq s \leq 0} | \phi(s) |$, and $| \cdot |$ is any convenient norm in \mathbb{R}^n . For a positive constant H , C_H denotes the set of $\phi \in C$ with $\| \phi \| < H$.

If $x : (t_0 - h, T) \rightarrow \mathbb{R}^n$ ($0 \leq t_0 < T \leq \infty$) is continuous and $t \in (t_0, T)$, we define $x_t(s) = x(t+s)$ for $s \in [-h, 0]$. Let $x'(t)$ denote the right-hand derivative at x if it exists and is finite.

Consider the system

$$(A) \quad x'(t) = F(t, x_t)$$

where $F : \mathbb{R}_+ \times C_H \rightarrow \mathbb{R}^n$ is continuous, $\mathbb{R}_+ \equiv (0, \infty)$ and takes bounded sets into bounded sets. It is then known [4] that for each $t_0 \in \mathbb{R}_+$ and each $\phi \in C_H$ there is at least one solution $x(t, t_0, \phi)$ satisfy (A) on an interval $[t_0, t_0 + \alpha)$ with $x_{t_0}(t_0, \phi) = \phi$ and with a value at t denoted by $x(t, t_0, \phi)$. Moreover, if there is an $H_1 < H$ and if $|x(t, t_0, \phi)| \leq H_1$ for all $t \geq t_0$ for which $x(t_0, \phi)$ can be defined, then $\alpha = \infty$.

Generalizing Lyapunov's classical stability theory on an ordinary differential equations to functional differential equations, Krasovskii [5] replaced the Lyapunov function $V : \mathbb{R}_+ \times \mathbb{R}^n \rightarrow \mathbb{R}$, with a continuous functional $V : \mathbb{R}_+ \times C_H \rightarrow \mathbb{R}$, whose derivative V' with respect to (A) was defined by

$$V'(t, \phi) = \lim_{\delta \rightarrow 0^+} \sup [V(t + \delta, x_{t+\delta}(t, \phi)) - V(t, \phi)] / \delta.$$

Throughout this discussion we work with wedges, denoted by W_i , which are continuous

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functions from R_+ to R_+ , which are strictly increasing, and which satisfy $W_1(0) = 0$. These wedges are related to properties of the Lyapunov functionals $V : R_+ \times C_H \rightarrow R$. We suppose that $F(t, 0) \equiv 0$ so that $x = 0$ is a solution of (A) and is called the *zero solution*.

1.1 Definition.

(a) The zero solution of (A) is *stable* if for each $\epsilon > 0$ there exists $\delta > 0$ such that $\{\phi \in C_\delta \text{ and } t \geq t_0\}$ imply $|x(t, t_0, \phi)| < \epsilon$.

(b) The zero solution of (A) is *asymptotic stable* if it is stable and if for each $t_0 \geq 0$ there is a $\tau = \tau(t_0) > 0$ such that $\phi \in C_\tau$ implies that $|x(t, t_0, \phi)| \rightarrow 0$ as $t \rightarrow \infty$.

2. Main Results

2.1 Theorem Let $V : R_+ \times C_H \rightarrow R_+$ be continuous and let τ be a measurable function from R_+ to R_+ such that

$$\liminf_{t \rightarrow \infty} \int_t^{t+\epsilon} \tau(s) ds > 0 \text{ for each } \epsilon > 0$$

Suppose that there are wedges W_1, W_2 and W_3 such that the inequalities:

$$i) 0 \leq V(t, \phi) \leq W_1(|\phi(0)|) + W_2(\|\phi\|)$$

and

$$ii) V'(t, \phi) \leq -\tau(t) W_3(|\phi(0)|)$$

hold for all $t \in R_+$ and $\phi \in C_H$.

Then for every bounded solution $x : [t_0 - h, \infty) \rightarrow R^n$ of (A), $\lim_{t \rightarrow \infty} V(t, x_t) = 0$

Proof. Suppose not. Then there exist $T > 0$ and $\epsilon > 0$ such that $\epsilon \leq V(t, x_t)$ for all $t \geq T$.

This implies

$$W_1(|x(t)|) \geq \frac{\epsilon}{2} \text{ or}$$

$$W_2(\|x_t\|) \geq \frac{\epsilon}{2} \text{ for any } t \geq T.$$

case 1) $W_1(|x(t)|) \geq \frac{\epsilon}{2}$ for any $t \geq T$.

By inequality ii), $\int_{t_0}^t V'(s, x_s) ds \leq - \int_{t_0}^t \tau(s) W_3(|x(s)|) ds$ holds. Therefore we have

$$V(t, x_t) - V(t_0, \phi) \leq - \int_{t_0}^t \tau(s) W_3(W_1^{-1}(\frac{\epsilon}{2})) ds,$$

and hence

$$V(t, x_t) \leq V(t_0, \phi) - \int_{t_0}^t \tau(s) W_3(W_1^{-1}(\frac{\epsilon}{2})) ds.$$

Now the right hand side of this inequality approaches to $-\infty$ as $t \rightarrow \infty$. This a contradiction to $V(t, \phi) \geq 0$.

case 2) $W_2(\|x_t\|) \geq \frac{\epsilon}{2}$ for all $t \geq T$.

Since W_2 is strictly increasing, $\|x_t\| \geq \delta$, where $\delta \equiv W_2^{-1}(\frac{\epsilon}{2})$. Now we note that each interval of length h contains an s such that $|x(s)| \geq \delta$.

Thus there exist a sequence $\{t_n\} \uparrow \infty$ as $n \rightarrow \infty$ such that for each $n = 1, 2, \dots$,

$$T + (2n-1)h \leq t_n \leq T + 2nh \text{ and } |x(t_n)| \geq \delta.$$

On the other hand, by the assumption on F , there exists a constant L such that

$$|x'(t)| < L \text{ for all } t \geq T.$$

Then

$$t_n - \frac{\delta}{2L} \leq t \leq t_n + \frac{\delta}{2L}.$$

So we have

$$|x(t)| \geq \frac{\delta}{2} .$$

That is,

$$\begin{aligned} \int_{t_0}^t V'(s, x_s) ds &\leq - \int_{t_0}^t \tau(s) W_s(|x(s)|) ds \\ &\leq - \sum_{n=1}^{\infty} \int_{I_n} \tau(s) W_s(|x(s)|) ds, \text{ where } I_n = (t_n \\ &- \frac{\delta}{2L}, t_n + \frac{\delta}{2L}) \\ &\leq -W_s(\frac{\delta}{2}) \sum_{n=1}^{\infty} \int_{I_n} \tau(s) ds \rightarrow -\infty \text{ as } t \rightarrow \infty, \end{aligned}$$

which is a contradiction. Hence we completes the proof.

2.2 Corollary Let $V : R_+ \times C_H \rightarrow R_+$ be continuous and let τ be a measurable function from R_+ to R_+ such that

$$\liminf_{t \rightarrow \infty} \int_t^{t+\epsilon} \tau(s) ds > 0 \text{ for each } \epsilon > 0$$

Suppose that there are wedges $W_i (i=1,2,3,4)$ and a constant K , where $0 < K < H$ such that the inequalities :

$$i) W_1(|\phi(0)|) \leq V(t, \phi) \leq W_2(|\phi(0)|) + W_3(|\phi|)$$

and

$$ii) V'(t, \phi) \leq -\tau(t) W_4(|\phi(0)|)$$

hold for all $t \in R_+$ and $\phi \in C_K$.

Then the zero solution of (A) is asymptotically stable.

Proof. Clearly, there is a wedge W_s with $V(t, \phi)$

$\leq W_s(|\phi|)$, so the zero solution is stable ([4, Theorem 5.2.1]). Let $t_0 \in R_+$ be given and define $r = r(t_0) = r(K, t_0) > 0$ where $r(K, t_0)$ is chosen from the Lyapunov stability. Let $\phi \in C_r$. We will show that $V(t, x_t(\cdot, t_0, \phi)) \rightarrow 0$ as $t \rightarrow \infty$, yielding $|x(t, t_0, \phi)| \rightarrow 0$ as $t \rightarrow \infty$. By way of contradiction, we have the similar proof of the preceding theorem.

3. An Example

Consider the scalar quation (2),(3)

$$(B) \quad x'(t) = -a(t)x(t) + b(t)x(t-h)$$

where $a, b: R_+ \rightarrow R$ are continuous such that for $t \in R_+$

$$a(t) \geq (1+K) |b(t+h)| \text{ for some } K > 0$$

Assume that $\tau(t) = |b(t+h)|$ has a property such that

$$\liminf_{t \rightarrow \infty} \int_t^{t+\epsilon} |b(s)| ds > 0 \text{ for each } \epsilon > 0$$

and

$$\int_{t-h}^t |b(u+h)| du \leq C \text{ for some } C > 0$$

Then the zero solution of (B) is asymptotically stable.

Proof. Consider the Lyapunov functional

$$V(t, x_t) = |x(t)| + \int_{t-h}^t |b(u+h)| |x(u)| du$$

Then

$$\begin{aligned} V(t, x_t) &\leq |x(t)| + \int_{t-h}^t |b(u+h)| |x(u)| du \\ &\leq |x(t)| + \int_{t-h}^t |b(u+h)| \|x_t\| du \\ &\leq |x(t)| + C \|x_t\| \end{aligned}$$

$$\begin{aligned} &= -a(t) |x(t)| + |b(t)| |x(t-h)| \\ &+ |b(t+h)| |x(t)| - |b(t)| |x(t-h)| \\ &\leq -a(t) |x(t)| + |b(t+h)| |x(t)| \\ &= -[a(t) - |b(t+h)|] |x(t)| \\ &\leq -K |b(t+h)| |x(t)| \end{aligned}$$

Let $W_1(t) = W_2(t) = W_3(t) = t$.

We have

$$W_1(|x(t)|) \leq V(t, x_t) \leq W_2(|x(t)|) + W_3(C \|x_t\|)$$

Moreover,

$$V'(t, x_t) = (|x(t)|)' + |b(t+h)| |x(t)| - |b(t)| |x(t-h)|$$

Let $W_4(t) = Kt$. Then

$$V'(t, x_t) \leq -\tau(t) W_4(|x(t)|)$$

By the corollary 2.2, the zero solution of (B) is asymptotically stable.

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〈國文抄錄〉

함수 미분 방정식에서의 점근 안정성

본 논문에서는 어떤 함수 미분방정식의 해, 영의 점근적 안정성을 직접적인 Lyapunov 방법을 이용하여 연구하고 그 예를 하나 들었다.